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**Zemlyakov S.D., Danilova E.A.**

The problem of nonstationary relay system analysis and synthesis is considered. The paper shows the opportunity of finding the design parameters under which the motion of the system described by a reduced mathematical model is asymptotically globally stable. For a special case, it is proved that the motion of the system described by the complete model converges to some domain that includes the desirable motion. Convergence domain construction technique is offered.

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